# Performance Assessment of Control Loops

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Abstract: The main concern of this thesis is to assess control loop performance using minimum variance control by FCOR algorithm in a convenient way by using only reactine operating data and comparing the outcomes with an existing algorithm (named PINDEN). Only by determining a performance factor of the feed-back control loop the controller performance could be assessed, even from thousands of control loops in process industries. Minimum variance is the benchmark which indicates attainable minimum variance against the actual variance of the control error. A performance index has been defined as the ratio of minimum variance to actual variance. Where, a performance index value close to I indicates poor control. The performance index is always a performance of to I. The performance index calculation algorithm was implemented using MATLAB. A dynamic simulation study was performed using Aspen HYSIS for generating process data and also by SEMULINK. Various cases such as noise corruption, stiction and oscillation were introduced and the aftermath was studied and analyzed. Industrial data from an Ammonia plant (SAPCO) was also analyzed. All the results are compared with previously developed algorithm. This thesis will help to outline a very simple but effective way to detect performance of the controller in process systems.

Keywords: FCOR, SISO, Performance Index, Feed-back Controlling.

#### 1. Introduction

In any chemical complex the foremost endeavor for any chemical engineer is to-make money save money. In process controlling it is very indispensable to get some quick idea that all the controller in control loops working satisfactorily or not. If this checking upon collection of process data could be done within a very short time then the frequency of online checking could be enhanced. So it is very important to take decision about replacing any existing controller or keeping it in accordance with its performance factor. As a relevance to this praematic demand, the main objective is to assess control loops performance by applying minimum variance control law, using closed loop process data. According to minimum variance controlling minimum variance is the benchmark which indicates attainable minimum variance against the actual variance of the control error. A performance index has been defined as the ratio of minimum variance to actual variance of the control loop. Thus performance index value close to 1 indicates good control while value close to 0 indicates poor control. The performance index value is always bounded between 0 to1. For performance index evaluation, algorithm implemented using MATLAB.

#### 2. About Methodology

A controller performance assessment technique has been developed using the routine operating data for univariate control loops, assuming that control objective is to reduce process variance; this conventional approach is termed as Minimum Variance Control. It is used naturally as the benchmark standard against which current control loop performance is assessed. It has been acknowledged that a system with time delay at a portion of output variance is feedback control invariant and can be estimated from routine operating data. This portion of output variance equals the variance achieved under minimum variance control; thus the method for the estimation of the minimum variance from routine operating data is established. Observed minimum variance for any system means theoretically achievable absolute lower bound of output variance to assess control loop performance. Using minimum variance control as the benchmark does not mean that one has to implement such a controller on the actual process. This benchmark control may or may not be achievable in practice depending on several physical constraints. However, as a benchmark, it provides useful information such as how well the current controller and how much potential there is to improve controller performance further. If the controller indicates a good performance measure relative to minimum variance control, further tuning or re-designing of the control algorithm is neither necessary nor helpful. In this case, if further reduction of process variation is desired, implementation of other strategies such as feed forward control or re-engineering of the process itself may be necessary. On the other hand, if the controller indicates a poor performance measure, further analysis, such as model analysis, robustness analysis, constraint analysis etc may be necessary.

# <u>Performance Assessment Of Control Loops Performance</u> <u>Assessment Of Control Loops</u>

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and industrial staff working on control systems design maintenance or optimisation in all process industries Control Loop Performance Assessment with Closed-loop Subspace Identification Nima Danesh Pour, 2009 Frequency and Time-domain Techniques for Control Loop Performance Assessment Anand Vishnubhotla, 1997 **Decision Technologies** R. Neves-Silva, J. Watada, G.E. Phillips-Wren, 2013-06-13 The field of intelligent decision technologies is interdisciplinary in nature bridging computer science with its development of artificial intelligence information systems with its development of decision support systems and engineering with its development of systems This book presents the 45 papers accepted for presentation at the 5th KES International Conference on Intelligent Decision Technologies KES IDT 2013 held in Sesimbra Portugal in June 2013 The conference consists of keynote talks oral and poster presentations invited sessions and workshops on the applications and theory of intelligent decision systems and related areas The conference provides an opportunity for the presentation and discussion of interesting new research results promoting knowledge transfer and the generation of new ideas The book will be of interest to all those whose work involves the development and Emerging Electronics and Automation Peter Han Joo Chong, Akhtar application of intelligent decision systems Kalam, Antonio Pascoal, Manas Kumar Bera, 2022-11-09 This book constitutes peer reviewed proceedings of the International Conference on Emerging Electronics and Automation E2A 2021 The book presents new ideas research findings and novel techniques in the fields of sensors and instrumentation automation and control artificial intelligence MEMS sensors soft computing signal processing and communication It includes contributions received from both academia and industry The proceedings will be helpful for beginners as well as advanced researchers in the area of automation and other allied fields

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design best practices and monitoring to sustain profit improvements Step by step guides to identifying building and deploying improvement applications For leaders and technologists in the industry who want to maximize profit margins this text provides basic concepts guidelines and step by step guides specifically for the chemical plant sector Assessment and Root Cause Analysis of Multivariable PID Control Loops Mehmet Yağcı.2016 **Control Performance** Assessment: Theoretical Analyses and Industrial Practice Paweł D. Domański, 2019-09-01 This book presents a comprehensive review of currently available Control Performance Assessment methods It covers a broad range of classical and modern methods with a main focus on assessment practice and is intended to help practitioners learn and properly perform control assessment in the industrial reality Further it offers an educational guide for control engineers who are currently in high demand in the industry The book consists of three main parts Firstly a comprehensive review of available approaches is presented and discussed The classical canon methods are extended with a discussion of nonlinear and complex alternative measures using non Gaussian statistics persistence and fractional calculations Secondly the methods applicability aspects are visualized with the aid of computer simulations covering the most popular control philosophies used in the process industry Lastly a critical review of the methods discussed on the basis of real world industrial examples rounds out IEE Seminar Control Loop Performance Assessment, Performance Evaluation, Prediction and Visualization of Parallel Systems Xingfu Wu,1999-02-28 Performance Evaluation Prediction and Visualization in Parallel Systems presents a comprehensive and systematic discussion of theoretics methods techniques and tools for performance evaluation prediction and visualization of parallel systems Chapter 1 gives a short overview of performance degradation of parallel systems and presents a general discussion on the importance of performance evaluation prediction and visualization of parallel systems Chapter 2 analyzes and defines several kinds of serial and parallel runtime points out some of the weaknesses of parallel speedup metrics and discusses how to improve and generalize them Chapter 3 describes formal definitions of scalability addresses the basic metrics affecting the scalability of parallel systems discusses scalability of parallel systems from three aspects parallel architecture parallel algorithm and parallel algorithm architecture combinations and analyzes the relations of scalability and speedup Chapter 4 discusses the methodology of performance measurement describes the benchmark oriented performance test and analysis and how to measure speedup and scalability in practice Chapter 5 analyzes the difficulties in performance prediction discusses application oriented and architecture oriented performance prediction and how to predict speedup and scalability in practice Chapter 6 discusses performance visualization techniques and tools for parallel systems from three stages performance data collection performance data filtering and performance data visualization and classifies the existing performance visualization tools Chapter 7 describes parallel compiling based search based and knowledge based performance debugging which assists programmers to optimize the strategy or algorithm in their parallel programs and presents visual programming based performance debugging to help

programmers identify the location and cause of the performance problem It also provides concrete suggestions on how to modify their parallel program to improve the performance Chapter 8 gives an overview of current interconnection networks for parallel systems analyzes the scalability of interconnection networks and discusses how to measure and improve network performances Performance Evaluation Prediction and Visualization in Parallel Systems serves as an excellent reference for researchers and may be used as a text for advanced courses on the topic **Bendix Technical Journal**, 1968

Multivariate Statistical Methods for Control Loop Performance Assessment Biao Huang, 1997 The Canadian AIChE Symposium Series American Institute of Chemical **Journal of Chemical Engineering**, 2007-08 Control Loop Performance Assessment and Oscillation Detection [microform] Lahoucine Ettaleb,1999 Engineers, 1997 Advanced Research on Information Science, Automation and Material System Helen Zhang, Gang Shen, David Jin, 2011-03-28 Selected peer reviewed papers from the 2011 International Conference on Information Science Automation and Material System ISAM 2011 May 21 22 2011 Zhengzhou China Tuning and Control Loop Performance, Fourth Edition Gregory K. McMillan, 2014-12-18 Tuning and Control Loop Performance Fourth Edition provides the knowledge to eliminate the misunderstandings realize the difference between theoretical and industrial application of PID control address practical difficulties improve field automation system design use the latest PID features and ultimately get the best tuning settings that enables the PID to achieve its full potential The proportional integral derivative PID controller is the heart of every control system in the process industry Given the proper setup and tuning the PID has proven to have the capability and flexibility needed to meet nearly all of industry s basic control requirements However the information to support the best use of these features has fallen behind the progress of improved functionality Additionally there is considerable disagreement on the tuning rules that largely stems from a misunderstanding of how tuning rules have evolved and the lack of recognition of the effect of automation system dynamics and the incredible spectrum of process responses disturbances and performance objectives

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